

SFB 991

Syntax-Driven Semantic Frame Composition in Lexicalized Tree Adjoining Grammars

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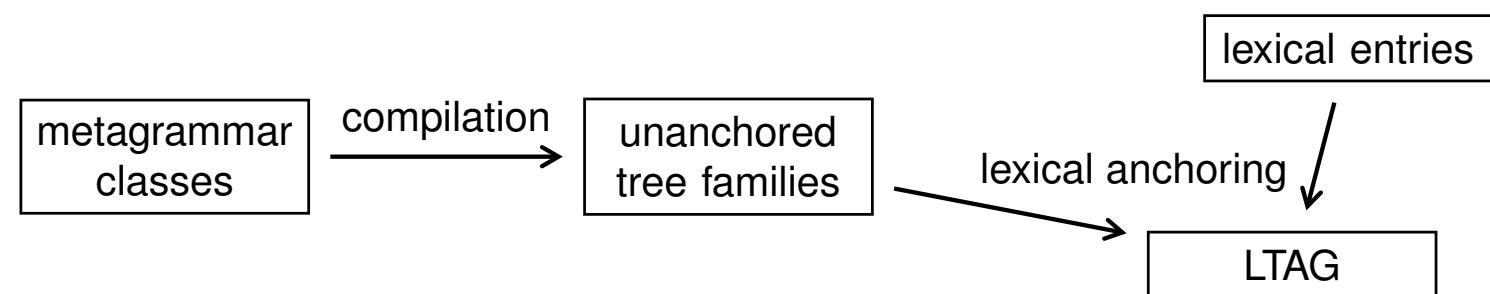
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Project goals

- Development of a grammar engineering framework that integrates lexical and constructional semantics and allows a fine-grained factorization into syntactic and semantic components.
- Method: Combination of Lexical Tree Adjoining Grammar (LTAG) and decompositional frame semantics.

LTAG and grammatical factorization

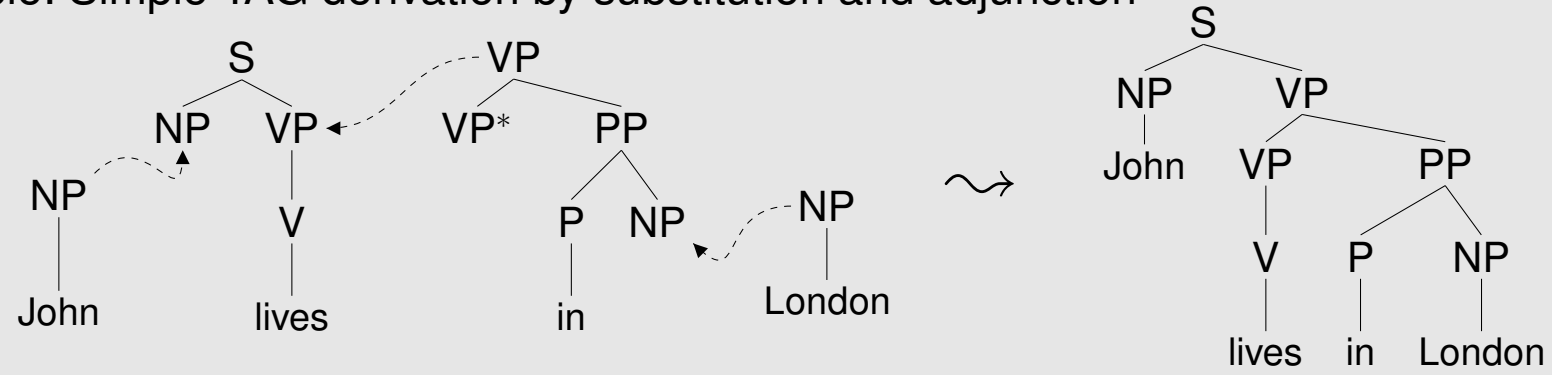
Overview



Lexicalized Tree Adjoining Grammar (LTAG) (Joshi & Schabes 1997)

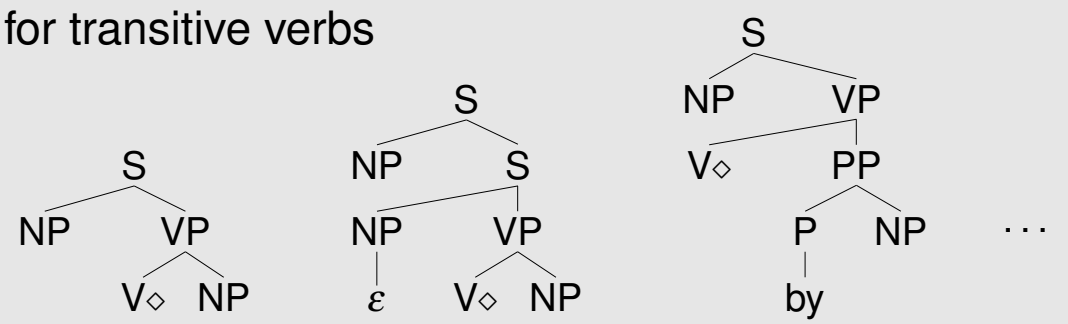
- Tree rewriting system (TAG) on *elementary trees* with two operations: *substitution* and *adjunction*.

Example: Simple TAG derivation by substitution and adjunction



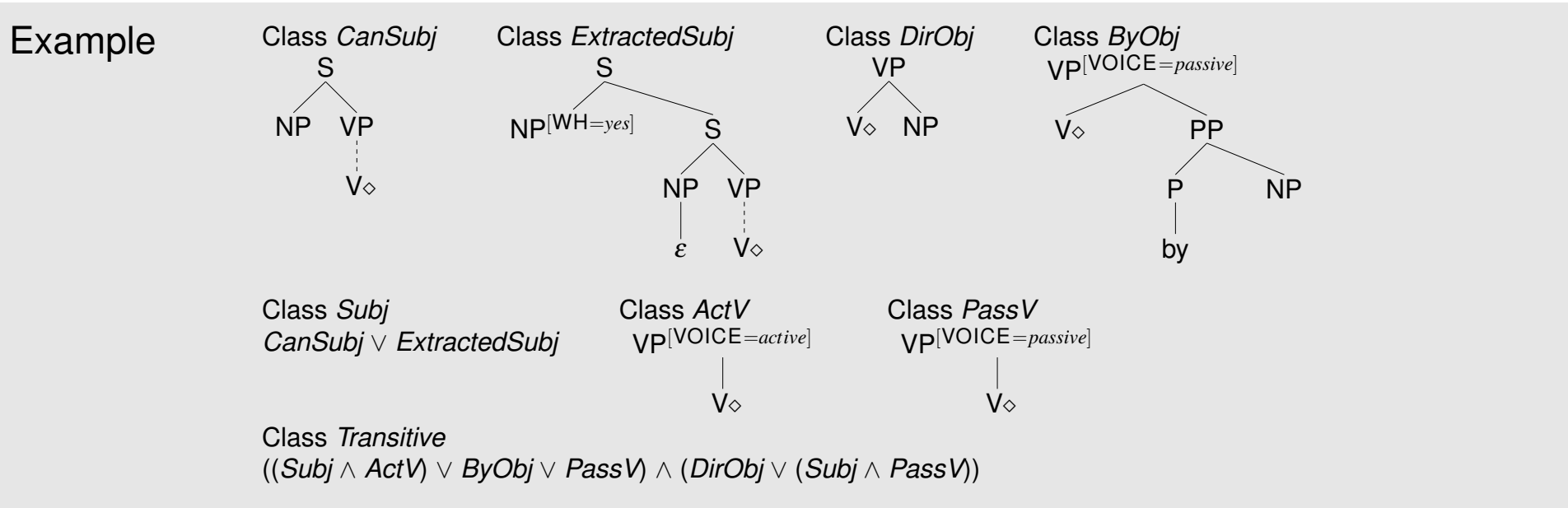
- Elementary trees are lexically anchored and they can be arbitrarily large (*extended domain of locality*).
- Elementary trees can be split into *lexical anchors* and *unanchored trees*, which are organized in *tree families* that represent subcategorization frames.

Example: Unanchored tree family for transitive verbs



Metagrammar (Candito 1999, Crabbe & Duchier 2005)

- Constraint-based, factorized description of unanchored elementary trees.

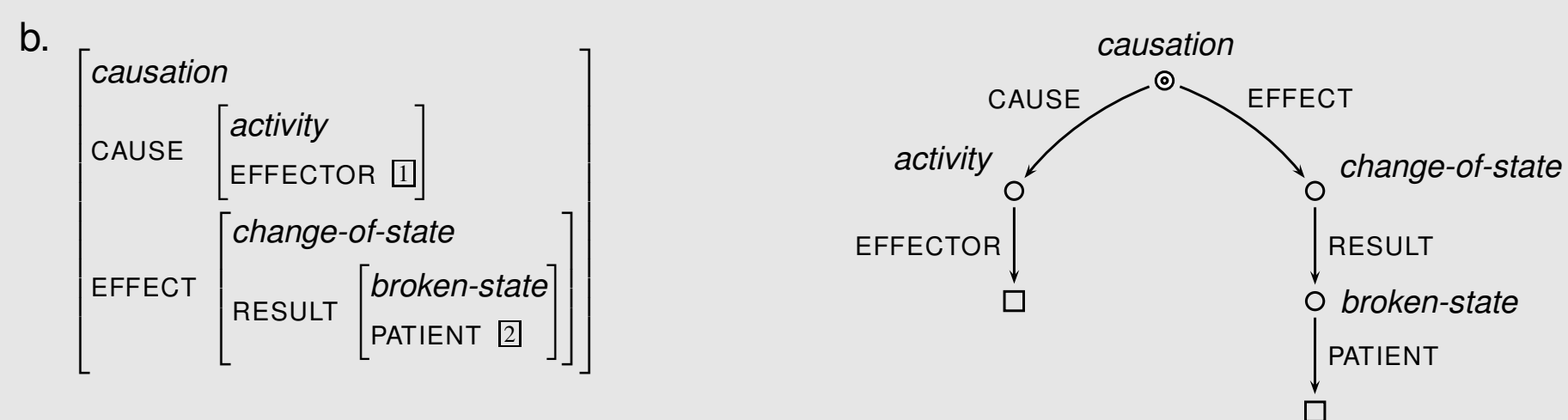


Decompositional frame semantics

- Concept centered with inherent structural properties (vs. event logic).
- Much more flexible than traditional decompositional templates.

Example: Decompositional representations of causative *break*

a. $[[x \text{ ACT}] \text{ CAUSE} [\text{BECOME} [y \text{ BROKEN}]]]$ (traditional decompositional template)



c. $\exists e \exists e' \exists e'' \exists s [\text{causation}(e) \wedge \text{CAUSE}(e, e') \wedge \text{EFFECT}(e, e'') \wedge \text{activity}(e') \wedge \text{EFFECTOR}(e', x) \wedge \text{change-of-state}(e'') \wedge \text{RESULT}(e'', s) \wedge \text{broken-state}(s) \wedge \text{PATIENT}(s, y)]$

Case study: the English dative alternation

- (1) a. John sent Mary the book. (double object, DO)
 b. John sent the book to Mary. (prepositional object, PO)

Traditional decompositional analysis:

- (2) a. $[[x \text{ ACT}] \text{ CAUSE} [z \text{ HAVE } y]]$ (caused possession)
 b. $[[x \text{ ACT}] \text{ CAUSE} [y \text{ GO TO } z]]$ (caused motion)

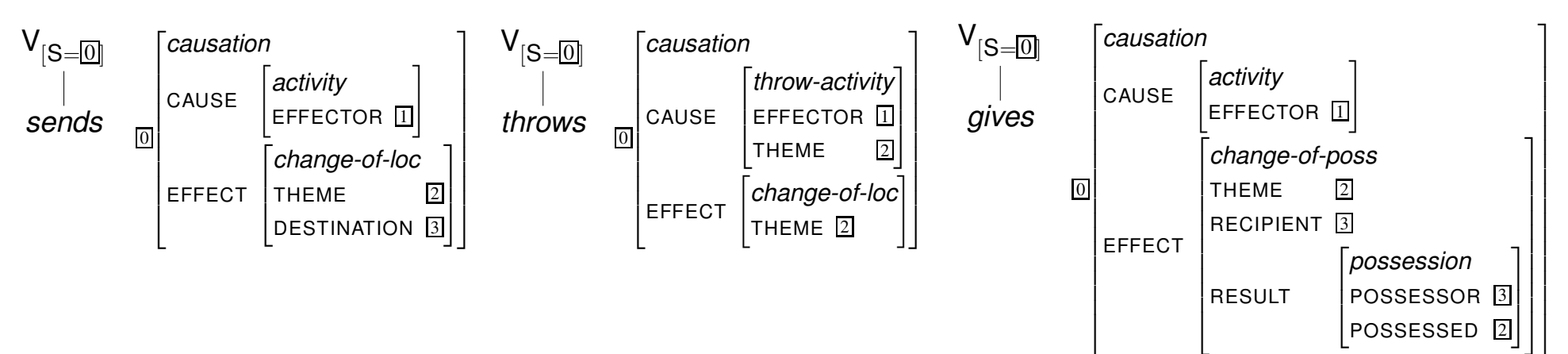
Observation (inter alia, Krifka 2004, Rappaport Hovav & Levin 2008):

- The interpretations of the DO and the PO constructions are sensitive to the lexical semantics of the verb.

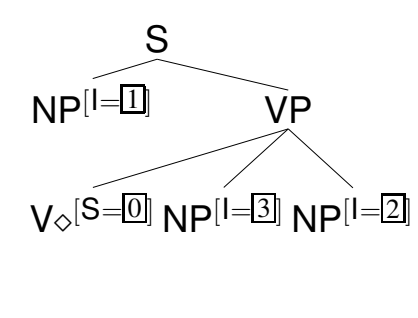
Partial semantic classification of alternating verbs (cf. Beavers 2011)

	#args	lexical meaning				PO pattern	DO pattern
		result	punct.	manner	motion	(◇arrive)	(◇receive)
<i>give</i>	3	receive	yes	no	no	receive	receive
<i>hand</i>	3	receive	yes	yes	yes	receive	receive
<i>send</i>	3	leave ◇arrive	yes	no	yes	◇arrive	◇receive
<i>throw</i>	2	leave	yes	yes	yes	◇arrive	◇receive
<i>bring</i>	3	arrive	no	no	yes	arrive	receive

Sketch of lexical and constructional frames



DO construction



PO construction

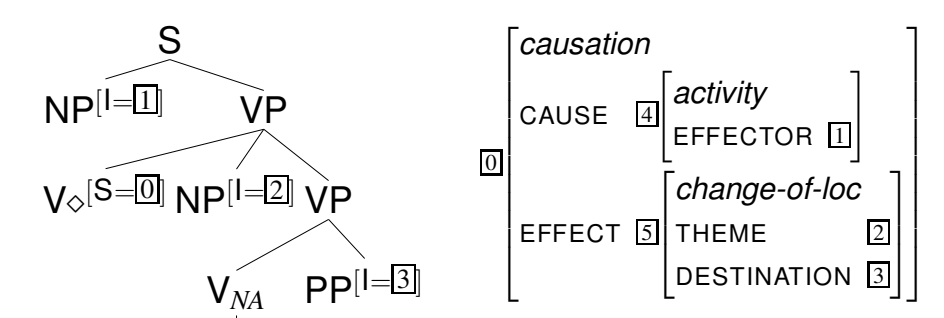


Illustration of metagrammatical factorization

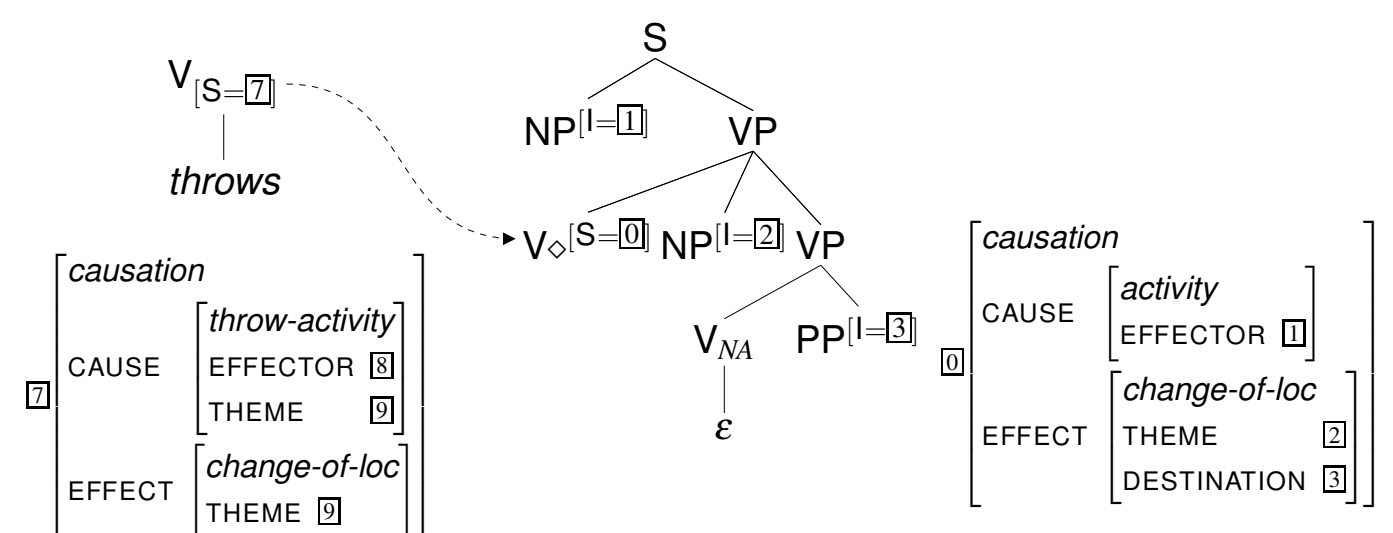
Class *Transitive*
 export: p, arg_1, arg_2
 use classes $V_1 = \text{InTransitive}$
 $N_2 = \text{DirObj}$
 identities: $V_1, V = N_2, V$
 $p = N_2, p$
 $arg_1 = V_1, arg_1$
 $arg_2 = N_2, x$

Class *IndirObj*
 export: x, p
 identities: $x = \square, p = \square$
 syntactic dimension
 VP
 $V_{\diamond} [S = \square] NP [I = \square]$
 V < NP
 semantic dimension
 $\square [\text{causation} [\text{EFFECTOR} [\text{change-of-poss}]]]$

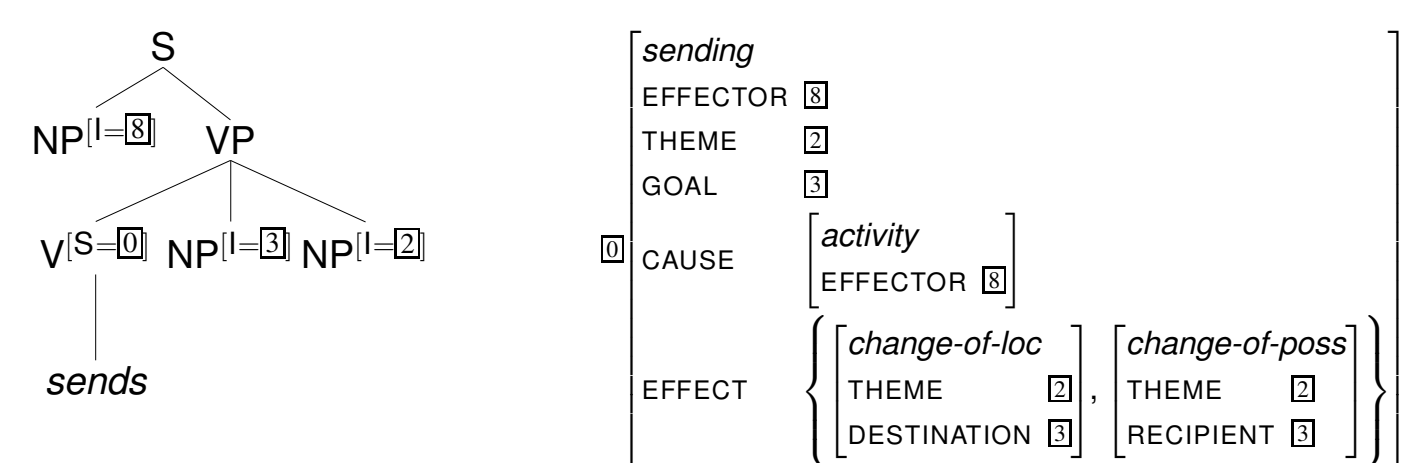
Class *DOConstr*
 export: p
 use classes $V_1 = \text{Transitive}$
 $N_3 = \text{IndirObj}$
 identities: $p = N_3, p$
 semantic dimension
 $p [\text{causation} [\text{EFFECTOR } V_1, arg_1 [\text{activity}]]]$
 $[\text{THEME } V_1, arg_2 [\text{change-of-loc}]]$
 $[\text{GOAL } N_3, x [\text{change-of-poss}]]$
 $[\text{CAUSE } [\text{EFFECTOR } V_1, arg_1]]$
 $[\text{EFFECT } [\text{THEME } V_1, arg_2]]$

Examples of lexical anchoring

- Process of anchoring the PO construction by *throws*:



- Result of anchoring the DO construction by *sends*:



Ongoing and future work

- Systematic definition of syntactic classes and generation of tree families.
- Larger coverage of constructions and more detailed semantic frames.
- Implementation by means of the XMG und TuLiPA tools.